## Claims

- [c1] 1. A method of motion detection for a 3D comb filter video decoder, suitable for use in a National Television Standards Committee (NTSC) system, comprising: sampling a composite video signal to obtain and register a plurality of sampling data  $F_{m}P_{x,y}$ , wherein  $F_{m}P_{x,y}$  represents a sampling data of the composite video signal from the  $m^{th}$  frame in  $x^{th}$  line at  $y^{th}$  pixel; and judging whether the composite video signal to be a motion state or a still state, according to the sampling data of  $F_{m+1}P_{x,y}$ ,  $F_{m}P_{x,y}$ ,  $F_{m-1}P_{x,y}$ , and  $F_{m-2}P_{x,y}$ .
- [c2] 2. The method ofmotion detection recited in claim 1, wherein the step of judging whether the composite video signal to be the motion state or the still state comprises: using the sampling data of F P, F P, F P, and F P to calculate and obtain a plurality of maximum differences MD, wherein MD represents the maximum difference for the y<sup>th</sup> pixel in the x<sup>th</sup> line; selecting the maximum differences for any adjacent four pixels to take an average, for obtaining a plurality of motion factors MF, wherein MF represents the motion factor for the y<sup>th</sup> pixel in the x<sup>th</sup> line; and

detecting the motion factor MF to judge whether the composite video signal to be the motion state or the still state.

- 3. The method ofmotion detection recited in claim 2, wherein the step of sampling the composite video signal comprises using a sampling frequency, which is four times of a subcarrier signal of the composite video signal, to sample, wherein the subcarrier signal is sampled at phase angles of 0,  $0.5\pi$ ,  $\pi$ , and  $1.5\pi$ .
- 4. The method ofmotion detection recited in claim 3, wherein the MD is calculated by MD = Max{|F|P F|P| F P | }.
- [c5] 5. The method ofmotion detection recited in claim 4, wherein the MF<sub>x,y</sub> is obtained by: selecting the maximum differences for any adjacent four pixels including the MD<sub>x,y</sub>, and taking an average, so as to obtain a plurality of averaged maximum differences AMD<sub>x,h</sub>, wherein the AMD<sub>x,h</sub> represents the average maximum differences for the h<sup>th</sup> pixel of the x<sup>th</sup> line, in which h is a positive integer, and a calculation formula of AMD<sub>x,h</sub> =  $(MD_{x,h} + MD_{x,h+1} + MD_{x,h+2} + MD_{x,h+3}) / 4$  is used; and

taking a minimum from the averaged maximum differences, so as to obtain a motion factor  $MF_{x,y}$ , wherein  $MF_{x,y}$ 

represents the motion factor for the  $y^{th}$  pixel of the  $x^{th}$  line.

[c6] 6. The method ofmotion detection recited in claim 5, wherein a minimum is obtained from a number of the adjacent averaged maximum differences and the  $MF_{x,y}$  is obtained by

MFx,y = Min(AMDx,y, AMDx,y-1, AMDx,y-2, AMDx,y-3).

[c7] 7. The method ofmotion detection recited in claim 5, wherein a minimum is obtained from a number of the adjacent averaged maximum differences and the  $MF_{x,y}$  is obtained by

 $MF_{x,y} = Min(AMD_{x,y}, AMD_{x,y-3}).$ 

[08] 8. The method ofmotion detection recited in claim 5, wherein the step of detecting the motion factor  $MF_{x,y}$  to judge whether the composite video signal to be the motion state or the still state for the  $y^{th}$  pixel in the  $x^{th}$  line comprises:

providing a threshold value; and

comparing the MF with the threshold value, wherein the  $y^{th}$  pixel in the  $x^{th}$  line of the composite video signal is judged as the motion state when the MF is greater than the threshold value, otherwise the still state is judged.

[c9] 9. The method ofmotion detection recited in claim 8, wherein the  $MF_{x,y}$  is the motion factor for the  $m^{th}$  frame.